

Department of Electronics and Communication Engineering

Bachelor of Technology

Electronics and Communication
Engineering with Hons. in Embedded
Systems and Robotics

Curriculum

University Vision

We visualize Graphic Era (Deemed to be University) as an internationally recognized, enquiry driven, ethically engaged diverse community, whose members work collaboratively for positive transformation in the world, through leadership in teaching, research and social action.

University Mission

The mission of the university is to promote learning in true spirit and offering knowledge and skills in order to succeed as professionals. The university aims to distinguish itself as a diverse, socially responsible learning community with a high-quality scholarship and academic rigor.

Department Vision

The Department visualizes itself to become leading centre of learning in the field of Electronics & Communication Engineering with academic excellence in research to produce self-motivated, creative, and socially responsible engineers and specialists, ready to take up challenges of industrial development with ethics and societal commitment.

Department Mission

M1: To provide high quality contemporary education in the field of Electronics & Communication Engineering and professional ethics to its learners.

M2: To provide creative learning environment for the students to equip them with strong foundation for continuing higher education.

M3: To pursue research and develop insight knowledge of current and emerging technologies in Electronics & Communication Engineering to serve the needs of the society, industry, and scientific community.

M4: To prepare students to have creative and innovative thinking to develop them into socially responsible professionals

Program Educational Objectives (PEOs):

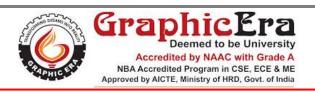
PEO1	Inculcation of an ability to realize and apply the subject-related knowledge to the real-world problems in the areas of electronics and communication engineering.
PEO2	Motivating individuals for team-led effort to investigate and provide ecologically sustainable, and cost-effective solutions to the problems in the subject area.
PEO3	Encouragement of competence in engineering computational and experimental capabilities to pursue research oriented higher education.
PEO4	Establishment of all-round environment for well conversant, socially and ethically responsible individuals with excellent communication skills.

Program Outcomes (POs):

PO1	Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
PO2	Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
PO3	Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
PO4	Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
PO5	Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
PO6	The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
PO7	Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
PO8	Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
PO9	Individual and teamwork: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
PO10	Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
PO11	Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
PO12	Life-long learning: Recognize the need for and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

Program Specific outcomes (PSOs):

PSO1	Create an ability to understand theoretical and practical concepts of Electronics and Communication Engineering and apply them in designing, fabrication, and testing of various Electronics & Communication system.
PSO2	The ECE Graduates will be able to analyze and implement engineering system pertaining to communication, Signal Processing, VLSI, Radio Frequency communication, microprocessor; microcontroller-based system design and embedded systems etc.
PSO3	This program enables the student to succeed in competitive exam like GATE, IES etc. and provides foundation for higher education and research.



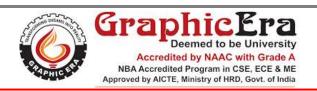
Program Course Structure (All Semesters)

B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2021 onwards)

Semester I & II

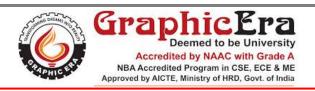
	COURSE		TEACHING PERIODS			WEIGHTAGE: EVALUATION				
THEORY	THEORY SUBJECT		CDEDITS	L	Т	P	CWA	MSE	ESE	TOTAL T
CODE	TITLE	COMPONENT	CREDITS	L	1	r	CWA	MSE	ESE	TOTAL
TEC 101/201	Basic Electronics Engineering	ESC	3	3	0	0	25	25	50	100
LABORA	TORY									
PEC 151/251	Basic Electronics Engineering Lab	ESC	1	0	0	2	25	25	50	100
	TOTAL		4	3	0	2				200



(Batch 2021 onwards)

Semester III

	COURSE M	MODULE			ACHI ERIO		WEIGHTAGE: EVALUATION			
THEOR	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL
CODE	TITLE	COMPONENT	CREDITS	L	1	r	CWA	MSE	ESE	IOIAL
TEC 301	Electronic Devices and Circuits	PCC	3	3	0	0	25	25	50	100
TEC 302	Digital Electronics	PCC	3	3	0	0	25	25	50	100
TEC 303	Networks Analysis and Synthesis	PCC	3	3	0	0	25	25	50	100
TEC 304	Signals and Systems	PCC	3	3	0	0	25	25	50	100
TEC 359	Fundamentals of Computer Organization	PCC	3	3	0	0	25	25	50	100
TMA 310	Advanced Engineering Mathematics	BSC	3	3	0	0	25	25	50	100
XCS 301	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 301	Electronics Circuit Lab	PCC	1	0	0	2	25	25	50	100
PEC 302	Digital Electronics Lab	PCC	1	0	0	2	25	25	50	100
PEC 303	Networks Lab	PCC	1	0	0	2	25	25	50	100
GP 301	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		24	20	0	06				1100



(Batch 2021 onwards) Semester IV

	COURSE M	MODULE		TEACHING PERIODS			WEIGHTAGE: EVALUATION			
THEORY	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL
CODE	TITLE	COMPONENT	CREDITS	L	•	•	CWII	MOL	LoL	TOTAL
TEC 401	Communication Systems I	PCC	3	3	0	0	25	25	50	100
TEC 402	Analog Integrated Circuits	PCC	3	3	0	0	25	25	50	100
TEC 403	Microprocessor and its Applications	PCC	3	3	0	0	25	25	50	100
TEC 404	Electromagnetic Field Theory	PCC	3	3	0	0	25	25	50	100
TEC 451	Introduction to Robotics	PCC	3	3	0	0	25	25	50	100
TOE	Open Elective I	OEC	3	3	0	0	25	25	50	100
XCS 401	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 401	Communication Systems I Lab	PCC	1	0	0	2	25	25	50	100
PEC 402	Analog Integrated Circuits Lab	PCC	1	0	0	2	25	25	50	100
PEC 403	Microprocessor Lab	PCC	1	0	0	2	25	25	50	100
POE	Open Elective Lab-I	OEC	1	0	0	2	25	25	50	100
GP 401	General Proficiency	GP	1	0	0	0	-	-	ı	100
	TOTAL		25	20	0	08				1200
Mandato	ry Non - Credit Course									
MC 401	Constitution of India	MC	0	0	0	0	0	0	0	0



(Batch 2021 onwards) Semester V

	COURSE MODULE				ACHI ERIO		WEIGHTAGE: EVALUATION			
THEOR	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL
CODE	TITLE	COMPONENT	CREDITS	L	1	P	CWA	MSE	ESE	IOIAL
TEC 501	Digital Signal Processing	PCC	3	3	0	0	25	25	50	100
TEC 502	Communication Systems II	PCC	3	3	0	0	25	25	50	100
TEC 503	Microcontroller and Embedded Systems	PCC	3	3	0	0	25	25	50	100
TEC 504	Antenna and Wave Propagation	PCC	3	3	0	0	25	25	50	100
TEC 551	Sensor Technology	PCC	3	3	0	0	25	25	50	100
TEC	Program Elective I	PEC	3	3	0	0	25	25	50	100
XCS 501	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS	1								
PEC 501	Digital Signal Processing Lab	PCC	1	0	0	2	25	25	50	100
PEC 502	Communication Systems II Lab	PCC	1	0	0	2	25	25	50	100
PEC 503	Microcontroller & Embedded Lab	PCC	1	0	0	2	25	25	50	100
PEC 559	Sensors Interfacing Lab	PCC	2	1	0	2	25	25	50	100
GP 501	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		26	21	0	08				1200



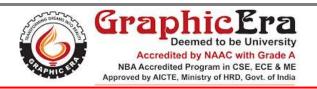
(Batch 2021 onwards) Semester VI

	COURSE M	IODULE			ACHI ERIO		WEIGHTAGE: EVALUATION			
THEOR	Y SUBJECTS			L	Т	P	CWA	MSE	ESE	тоты
CODE	TITLE	COMPONENT	CREDITS				CWA	MSE	ESE	TOTAL
TEC 601	Wireless Communication	PCC	3	3	0	0	25	25	50	100
TEC 602	Microwave Engineering	PCC	3	3	0	0	25	25	50	100
TEC 603	VLSI Technology and Design	PCC	3	3	0	0	25	25	50	100
TEC 659	Advanced Embedded Systems	PCC	3	3	0	0	25	25	50	100
TEC	Program Elective II	PEC	3	3	0	0	25	25	50	100
TOE	Open Elective II	OEC	3	3	0	0	25	25	50	100
XCS 601	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 601	CAD of Electronics using CADENCE Tool Lab	PCC	1	0	0	2	25	25	50	100
PEC 602	Microwave and Antenna Lab	PCC	1	0	0	2	25	25	50	100
PVL 603	Fading Channels and Mobile Communications	PCC	1	0	0	2	25	25	50	100
POE	Open Elective Lab-II	OEC	1	0	0	2	25	25	50	100
PMP 604	Mini Project	PROJ	1	0	0	2	25	25	50	100
GP 601	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		26	20	0	10				1300



(Batch 2021 onwards) Semester VII

	COURSE M	10DULE			TEACHING PERIODS WEIGHTAGE: EVALUATE					
THEOR	Y SUBJECTS		CDEDITE		Т	P	CWA	MOD	5 05	mom
CODE	TITLE	COMPONENT	CREDITS	L			CWA	MSE	ESE	TOTAL
TEC 701	Principles of Management	HSMC	3	3	0	0	25	25	50	100
TEC 759	Internet of Things and Its Applications	PCC	3	3	0	0	25	25	50	100
TEC	Program Elective III	PEC	3	3	0	0	25	25	50	100
TEC	Program Elective IV	PEC	3	3	0	0	25	25	50	100
TEC 731	Disaster Management	ESC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 701	Project Phase-I	PROJ	5	0	0	10	100	-	-	100
SEC 701	Seminar on Industrial Training	PROJ	1	0	0	2	100	-	-	100
PEC 759	Networking Lab	PCC	2	1	0	2	25	25	50	100
GP 701	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		23	15	0	14				900



(Batch 2021 onwards) Semester VIII

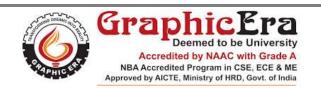
	COURSE MODULE				TEACHING PERIODS			WEIGHTAGE: EVALUATION			
THEOR	Y SUBJECTS		CREDITS	L	Т	P	CITA	MSE	ESE		
CODE	TITLE	COMPONENT	CREDITS	2		1	CWA			TOTAL	
TOE	Open Elective III	OEC	3	3	0	0	25	25	50	100	
TEC	Program Elective V	PEC	3	3	0	0	25	25	50	100	
TEC	Program Elective VI	PEC	3	3	0	0	25	25	50	100	
LABOR	ATORY AND OTHERS										
PEC 801	Project Phase-II	PROJ	9	0	0	18	50	-	150	200	
GP 801	General Proficiency	GP	1	0	0	0	-	-	-	100	
	TOTAL		19	9	0	18				600	



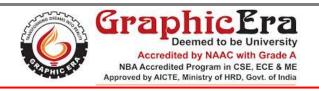
	Program Elective Courses						
Course Code	Course Name	Semester					
	Program Elective I						
TEC 552	Control Systems						
TEC 553	Electromagnetic Interference and Compatibility	T::64].					
TEC 554	High Speed Communication Circuits	Fifth					
TEC 555	Probability and Stochastic Processes						
	Program Elective II						
TEC 651	Data Communication Networks						
TEC 652	Digital VLSI Circuit Design	C!41					
TEC 653	Semiconductor Materials and Devices	Sixth					
TEC 654	Digital Video Processing						
	Program Elective III						
TEC 751	Optical Fiber Communications						
TEC 752	ASIC Design and FPGA	Carrandle					
TEC 753	Radar and Navigation Aids	Seventh					
TEC 754	Organic Electronics Devices and Circuits						
	Program Elective IV						
TEC 755	Wireless Sensor Network						
TEC 756	Fundamentals of Nanotechnology	Seventh					
TEC 757	CMOS Analog Circuit Design	Seventin					
TEC 758	Speech Processing						
	Program Elective V						
TEC 851	Satellite Communications						
TEC 852	Testing of VLSI circuits	Fighth					
TEC 853	Eighth						
TEC 854	Digital Image Processing						
	Program Elective VI						
TEC 855	Telecommunication Switching	Eighth					



TEC 856	Neural Networks & Machine Learning	
TEC 857	Mobile Ad hoc Networks	
TEC 858	Adaptive Signal Processing	



Open Elective Courses					
Course Code	Course Name	Semester			
	Open Elective-I				
TOE 410	Data Structures with C				
TOE 411	Electrical Machines-I	Fourth			
TOE 412	Computer Based Numerical and Statistical Technique	rourm			
	Open Elective Lab-I				
POE 410	Data Structures with C Lab				
POE 411	Electrical Machines Lab-1	Fourth			
POE 412	CBNST Lab				
	Open Elective-II				
TOE 610	Object Oriented Programming with C++				
TOE 611	TOE 611 Power Electronics				
TOE 612	Operating Systems				
	Open Elective Lab-II				
POE 610	OOPs with C++ Lab				
POE 611	Power Electronics Lab	Sixth			
POE 612	Operating Systems Lab				
	Open Elective-III				
TOE 810	Computer Architecture				
TOE 811	Electrical and Electronics Measuring Instruments	Eighth			
TOE 812	Biosensors and Bioelectronics				



Abbreviations:

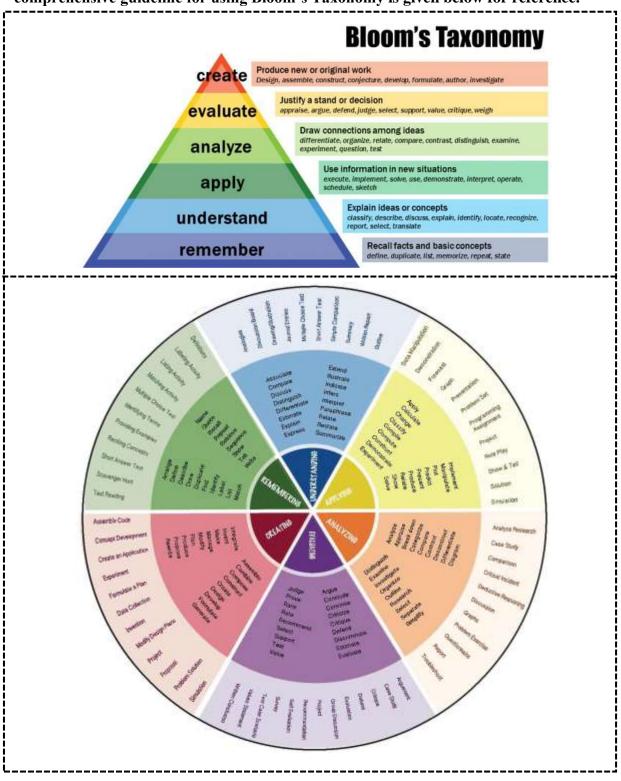
L	Lecture
T	Tutorial
P	Practical
CWA	Class Work Assessment
MSE	Mid Semester Exam
ESE	End Semester Exam
BSC	Basic Science Course
ESC	Engineering Science Course
HSMC	Humanities and Social Sciences including Management course
PCC	Professional Core Course
PEC	Professional Elective Course
OEC	Open Elective Course
MC	Mandatory Course
PROJ	Project
GP	General Proficiency

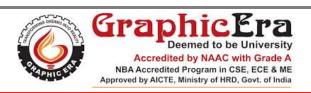


Bloom's Taxonomy for Curriculum Design and Assessment

Preamble

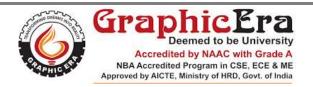
The design of curriculum and assessment is based on Bloom's Taxonomy. A comprehensive guideline for using Bloom's Taxonomy is given below for reference.





	Electronics and Communication Engineering Department						
Electronics and Communication Engineering Department B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and							
Robotics							
Semester Third		Subject Title	Fundamentals of Computer Organization		Code	TEC 359	
Course Co	omponents	Credits		L	T	P	
	onal Core e (PCC)	03	Contact Hours	3	0	0	
Exam	ination	Theory	W: 1/ E 1 /:	CWA	MSE	ESE	
Duratio	on (Hrs)	03	Weightage: Evaluation	25	25	50	
		Pre-requi	site: Basic Electronics				
		Со	urse Outcomes				
Upon com	pletion of th	is course, the stude	ents will be able to				
CO 1	Recall the	concepts of compute	er system and its organizati	on.			
CO 2			er Arithmetic operations an		ıms.		
CO 3	Understan	d different addressir	ng modes and instruction for	ormats.			
CO 4	Analyse n	• 0	n, cache memory mappi	ng and	paging to	improve	
CO 5			organization and control u	nit.			
CO 6	Assess and evaluate processor organization and control unit. Develop the concepts of computer organization for better understanding of courses, such as embedded system and robotics.						
Unit No.	Content Hours						
	Content					Hours	
Unit 1:	Introduction Structure of Historical of	of a computer syste development: First th	em, Functional component arough fourth generation co on Von Neumann model.			Hours 8	
	Introduction Structure of Historical of law, The V Machine In Memory loof formats, In	of a computer system development: First the on Neumann and Nonstructions: ocation and addressent struction sequencing		modes, In	Moore's		
Unit 1:	Introduction Structure of Historical of law, The V Machine In Memory lot formats, In Instruction Computer Addition and Division all	of a computer system development: First the on Neumann and Nonstructions: ocation and addressed architectures - Computer Arithmetic: and subtraction, Arithmetic architectures - Computer Section and Subtraction, Arithmetic and Subtraction, Arithmetic architectures - Computer Section and Subtraction architectures - Computer Section architectures - Computer Section architectures - Computer Section and Section architectures - Computer Section -	on Von Neumann model. es, Operands, Addressing and Execution of a communication of a communication of the communic	modes, In aplete inses.	Moore's astruction struction, gorithms,	8	
Unit 1: Unit 2:	Introduction Structure of Historical of law, The V Machine In Memory lot formats, In Instruction Computer Addition and Division all operations, Processing Organization and CPU, Instruction	of a computer system development: First the on Neumann and Nonstructions: ocation and addressement of the computer set architectures - Computer of the compute	on Von Neumann model. es, Operands, Addressing rang, Execution of a community and RISC architecture ithmetic circuit, Multiplic	modes, In aplete ins. eation algorithm and point a unit, Dart, Operati	Moore's astruction struction, gorithms, rithmetic ta path in ions of a	8	
Unit 1: Unit 2: Unit 3:	Introduction Structure of Historical of law, The V Machine In Memory lot formats, In Instruction Computer Addition and operations, Processing Organization and CPU, Instruction of Memory S Semicondulorganization memory, Maccess times	of a computer system development: First the on Neumann and Nonstructions: ocation and addressed astruction sequencing set architectures - Comparison of a control of a processor - Restruction cycle, Orgot, Hardwired control of a memory chall apping methods, Orgot and Hit ratio, oges of paging.	es, Operands, Addressing rang, Execution of a company and RISC architecture ithmetic circuit, Multiplication representation, Floating tegisters, ALU and Control anization of a control unit	modes, In aplete inses. cation algorithms and unit, Dart, Operationtrol unit. AM cells Concept ory unit,	Moore's astruction struction, gorithms, rithmetic ta path in ions of a tt. , Internal of cache Effective	8 8	

Textbooks



1.	William Stallings, "Computer Organization & Architecture Designing for Performance",
	Prentice Hall Education, 8th Edition, 2010.

2. Carl Hamacher, ZvonkoVranesic, SafwatZaky, "*Computer Organization*", Tata McGraw Hill, 5th Edition, 2011

Reference Books

- 3. David A. Patterson, John L. Hennessy: "Computer Organization and Design The Hardware / Software Interface", Morgan Kaufmann (Elsevier), 5th Edition, 2013.
- **4.** John P. Hayes, "Computer Architecture and Organization", Tata McGraw Hill, 3rd Edition, 2012.

Mode of Evaluation	Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



Electronics and Communication Engineering Department						
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics						
Semester Fourth		Subject Title	Introduction to Robotics Code		Code	TEC 451
Course Co	omponents	Credits		\boldsymbol{L}	T	P
	onal Core e (PCC)	03	Contact Hours	3	0	0
Exam	ination	Theory	Weightage: Evaluation	CWA	MSE	ESE
Duratio	on (Hrs)	03	weighiage. Evaluation	25	25	50
		Pre-requisite: I	Basic Electronics Engineeri	ng		
		Ca	ourse Outcomes			
	pletion of th	is course, the stud	ents will be able to			
CO 1			and key components of rol	botics tec	hnology.	
CO 2	Understan	d the control systen	ns related to robotics.			
CO 3	Model and	control single joint	t robot.			
CO 4	CO 4 Understand various robot sensors, end effectors and their perception principles.					
CO 5 Analyse the robot kinematics, navigation, and path planning.						
CO 6	CO 6 Understand machine vision and its digitizing function.					
Unit No.	Content					Hours
Unit 1:	Fundamentals of Robotics: Brief history of robotics, Robotics market, Future perspectives of robotics, robot anatomy, Robot drive systems, Precision of movement, End effectors.					
Unit 2:	Control System and Components: Basic control system concepts and model. Controllers. Robot sensors and			8		
Unit 3:	Robot End Effectors and Sensors:					
Unit 4:	Introduction		Control: kinematics, Homogeneou path control, Robot dynan		ormation,	6
Unit 5:			, Sensing and digitizing funalysis.	nction in	machine	6
		Total	l Hours			40

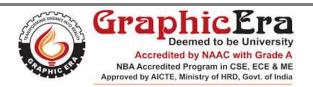
	Textbooks				
1.	M P Groover, "Industrial Robotics", TMH, 2 nd Edition, 2012.				
2.	S R Deb and Sankha Deb, "Robotics Technology and Flexible Automation", TMH, 2 nd Edition,				
	2010.				
	Reference books				
3.	S.K Saha, "Introduction to Robotics", TMH, 2 nd Edition, 2014				
4.	R.K. Mittal, I.J. Nagrath, "Robotics & Control", TMH, 2005.				
5.	Craig. J. J, "Introduction to Robotics- Mechanics and Control", Pearson Education India, 3rd				
	Edition, 1999.				

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



	Electronics and Communication Engineering Department						
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics							
Semester Fifth		Subject Title	Sensor Technology		Code	TEC 551	
Course Co	omponents	Credits		\boldsymbol{L}	T	P	
	onal Core (PCC)	03	Contact Hours	3	0	0	
Exami	ination	Theory	Weightage: Evaluation	CWA	MSE	ESE	
Duratio	on (Hrs)	03	Weightage. Evaluation	25	25	50	
	Pre-r		sics and Basic Electronics I	Engineeri	ng		
			urse Outcomes				
1	ì	nis course, the stude					
CO 1			he basic characteristics of	sensors.			
CO 2		d the working princi					
CO 3			th various electronic device				
CO 4	Apply the sensors.	concepts of sensor t	echnology in several types	s of motion	on and dis	placement	
CO 5	Evaluate s	ensors and interfacir	ng circuits				
CO 6	Utilize sen	sors in different engi	ineering applications.				
Unit No. Content Hours							
Unit 1:	I: Sensor Characteristics: Transfer function, Calibration, Span (Full-scale input), Full-scale output, Calibration error, Accuracy, Hysteresis error, Nonlinearity, Saturation, Repeatability, Dead band, Resolution, Reliability, Uncertainty.						
					aturation,	8	
Unit 2:	Repeatabili Physical P Electric ch law, Sole Pyroelectri	rinciples of Sensing arges, Fields and po- noid, Toroid, Inc c effect, Hall effe	lution, Reliability, Uncerta	ninty. agnetism: zoelectric t, Sound	Faraday effect, waves,	8	
Unit 2: Unit 3:	Repeatabili Physical P Electric ch law, Sole Pyroelectri Temperatur sensor. Interface I Input char converters, Inherent no	rinciples of Sensing arges, Fields and penoid, Toroid, Inc. effect, Hall effere, Dynamic models Electronic Circuits: acteristics of interfere Excitation circuits, Poise, Transmitted in	colution, Reliability, Uncertage cotentials, Capacitance, Maluction Resistance, Piesect, Thermoelectric effects of sensor elements, Option	ainty. agnetism: zoelectric t, Sound cal compo Light to s, Noise ir Bypass ca	Faraday effect, waves, onents of voltage a sensors:		
	Repeatabili Physical P Electric ch law, Sole Pyroelectric Temperatur sensor. Interface I Input char converters, Inherent no Magnetic s Motion an Ultrasonic sensors, Ca	rinciples of Sensing arges, Fields and penoid, Toroid, Inc. effect, Hall effere, Dynamic models Electronic Circuits: acteristics of interfere Excitation circuits, Poise, Transmitted inhielding, Mechanica detectors, Optoeles apacitive sensors, Inc.	elution, Reliability, Uncertages; otentials, Capacitance, Maduction Resistance, Pierect, Thermoelectric effect of sensor elements, Option and Cace circuits, Amplifiers, Analog to digital converters oise, Electric shielding, El noise, Ground planes, Sen	ainty. agnetism: zoelectric et, Sound cal compo Light to s, Noise in Bypass ca ebeck noi es, Poten or: LVDT	Faraday effect, waves, onents of voltage a sensors: apacitors, se	8	
Unit 3:	Repeatabili Physical P Electric ch law, Sole Pyroelectri Temperatur sensor. Interface I Input char converters, Inherent no Magnetic s Motion an Ultrasonic sensors, Ca Eddy curre Humidity Concept of	rinciples of Sensing arges, Fields and penoid, Toroid, Incompleted and penoid, Toroid, Incompleted argument of the Electronic Circuits: acteristics of interfaction circuits, acteristics of interfaction circuits, acteristics of interfaction, Mechanica dollar detectors, Optoeles apacitive sensors, Incompleted argument sensors, Transvers Sensors and Light Inhumidity, Electrical	dution, Reliability, Uncertage of the contentials, Capacitance, Maduction Resistance, Pier etc., Thermoelectric effect of sensor elements, Option of sensor elements, Option of sensor elements, Analog to digital converters oise, Electric shielding, El noise, Ground planes, Sensor: The content of the conte	ainty. agnetism: zoelectric st, Sound cal compo Light to s, Noise ir Bypass ca ebeck noi s, Poten or: LVDT ffect sense	Faraday effect, l waves, onents of voltage a sensors: apacitors, se tiometric r, RVDT, or.	8	

Textbooks	

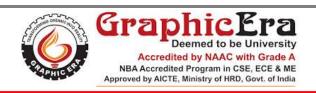


1.	Jacob Fraden, "Handbook of modern sensors: physics, designs, and applications", Springer,
	4th Edition, 2005

Reference books

- 2. C.M. Kyung, H. Yasuura, Y. Liu, Y. L. Lin, "Smart Sensors and Systems: Innovations for Medical, Environmental, and IoT Applications", Springer, 2016.
- 3. Jon Wilson, "Sensor Technology Handbook", Volume 1, Elsevier, 2004.

Mode of Evaluation	Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



	Depo	ertment of Electron	ics and Communication E	ngineerin	ıg		
B. Tech in	n Electronic	s and Communicati	ion Engineering with Hons Robotics	s. in Emb	edded Sysi	tems and	
Semester	Fifth	Subject Title	Sensors Interfacing Lab		Code	PEC 559	
Course Co	omponents	Credits		\boldsymbol{L}	T	P	
	onal Core (PCC)	02	Contact Hours	1	0	2	
Exami	ination	Practical	III . 1	CWA	MSE	ESE	
Duratio	on (Hrs)	03	Weightage: Evaluation	25	25	50	
		Pre-requisite: Mic	croprocessor and its applica	tions			
		Ce	ourse Outcomes				
Upon com	pletion of th	is course, the stud	ents will be able to				
CO 1	Recall the sensors.	basic concepts of	TM4C123GXL, MSP430G	2, Ardui	no Uno an	d various	
CO 2	Understand the concepts of interfacing of sensors with Texas boards and Arduino Boards.						
CO 3	Analyse various interfacing boards with IoT.						
CO 4	Apply various transducers and actuators interfacing in the designing of embedded and IoT systems.						
E. N.	N C 41	E. E					
Exp. No.	Name of the Experiment Familiarization of TIVA C-series 12 launch pad (TM/C123GYL)						
1.	Familiarization of TIVA C-series 12 launch pad (TM4C123GXL) Interfacing of sensors with TIVA C-series 12 launch pad (TM4C123GXL)						
2. 3.	Interfacing of sensors with TIVA C-series12 launch pad (TM4C123GXL) Interfacing of sensors with cloud using TIVA C-series12 launch pad (TM4C123GXL)						
<i>3. 4.</i>	Interfacing of sensors with cloud using TIVA C-series12 launch pad (TM4C123GXL) Interfacing of keypad with TIVA C-series12 launch pad (TM4C123GXL)						
<i>5</i> .	Familiarization of MSP430G2 launch pad. (1M4C123GXL)						
<i>6</i> .	Interfacing of sensors with MSP430G2 launch pad.						
<i>7</i> .	Interfacing of sensors with MSP430G2 faunch pad. Interfacing of sensors with cloud using MSP430G2 faunch pad.						
8.	Interfacing of sensors with cloud using MSF450G2 faunch pad. Interfacing of keypad with MSP430G2 launch pad.						
9.	Familiarization of Arduino Microcontroller.						
10.	Interfacing of sensors with Arduino Microcontroller.						
11.	Interfacing of keypad with Arduino Microcontroller.						
12.	Interfacing of servo motor with TIVA C-series12 launch pad (TM4C123GXL)						
	Experiment			\		/	
13.		of servo motor with	n MSP430G2				
<i>14</i> .			suggestion of Lab In charg	e.			

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam



	Ele	ctronics and Comn	nunication Engineering De	partmen	t	
B. Tech i	n Electronics	s and Communicat	ion Engineering with Hons Robotics	. in Emb	edded Sysi	tems and
Semester	Sixth	Subject Title	Advanced Embedded Systems Code		Code	TEC 659
Course Co	omponents	Credits		\boldsymbol{L}	T	P
Professional Core Course (PCC)		03	Contact Hours	3	0	0
Examination Duration (Hrs)		Theory 03	Weightage: Evaluation	<i>CWA</i> 25	MSE 25	ESE 50
Dirimi			ocontroller & Embedded Sy		23	30
			ourse Outcomes	sterns		
Upon com	pletion of th		ents will be able to			
CO 1	Recall the	working concept of	microprocessor and microc	ontroller		
CO 2	Understan	d the architecture a	nd instruction sets of PIC m	icrocont	rollers.	
CO 3	Relate the	knowledge of syste	m design and peripheral into	erfacing.		
CO 4	Analyse str	ructure of RTOS in	Embedded Systems.			
CO 5	Evaluate P	PIC and ARM proce	essors as the advanced series	3.		
CO 6	Integrate t	he concepts of emb	edded systems for developi	ng projec	ts.	
Unit No.	Content					Hours
Unit 1:	Introduction to Embedded systems: Embedded systems vs. General computing systems, History of embedded systems, Classification, Application area. Typical embedded systems, Characteristics and quality attributes of embedded systems.				8	
Unit 2:	Intel Family of Microcontrollers PIC Architectures: PIC series of microcontrollers, Instruction set, Addressing modes, Interrupts and timer.				8	
Unit 3:	System Design, Peripheral Interfacing: Digital and analog interfacing, Programming framework, Software development.				8	
Unit 4:	Real Time Operating Systems (RTOS): Embedded systems design, Operating system basics, Types of operating system tasks, Process, Threads, Multiprocessing and Multitasking, Task scheduling.				8	
Unit 5:	ARM 32-		ers: A bus architecture, Brief hitecture and overview.	introdu	ection to	8
		Tota	l Hours			40

	Textbooks		
1.	Raj Kamal ," <i>Microcontrollers: Architecture, Programming, Interfacing and System Design</i> ", Pearson Education India, 2 nd Edition, 2005.		
2.	J. Morton, "The PIC Microcontroller", Newnes, 3 rd Edition, 2005.		
Reference Books			
3.	A. Sloss, D. Symes, C. Wright, "Arm System Developer's Guide: Designing and optimizing system software", Morgan Kauffman Publisher, Illustrated edition, 2004.		
	K. V. Shibhu, "Introduction to Embedded Systems", Tata McGraw Hill, 1st Edition, 2009.		

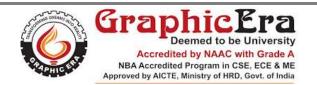


5. Frank Vahid, Tony Givargis, "Embedded System Design, A Unified Hardware, Software Approach", Wiley Publications, 3rd Edition, 1999.

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



	Elec	tronics and Commi	unication Engineering De	partment	<u>,</u>	
B. Tech in			on Engineering with Hons Robotics			tems and
Semester	Seventh	Subject Title	Internet of Things and Its Applications Code		TEC 759	
	omponents	Credits		L	T	P
	onal Core e (PCC)	03	Contact Hours	3	0	0
Exam	ination	Theory	Weightage Englishing	CWA	MSE	ESE
Duratio	on (Hrs)	03	Weightage: Evaluation	25	25	50
			Wireless Communication			
		Cor	urse Outcomes			
		is course, the stude				
CO 1	Recall the k	nowledge of wireles	ss sensor network and Inter	rnet of the	ings.	
CO 2	Understand	l IoT Market perspe	ctive.			
CO 3	Apply the S	tate of the Art – IoT	architecture.			
CO 4	Analyse the	applications of IoT				
CO 5	Assess and	evaluate IoT applica	ations for privacy, security	, and gov	ernance.	
CO 6	Design and	develop various IoT	based applications.			
Unit No.	Content					Hours
Unit 1:	Introduction to sensor networks, Unique constraints and challenges, Advantage of sensor networks, Defining IoT, Characteristics of IoT, Physical design of IoT: Things in IoT, Physical design, Logical design of IoT, Functional blocks of IoT, IoT communication models, Applications of sensor networks in IoT.					8
Unit 2:	M2M to IoT – A Basic Perspective: Introduction, some definitions, M2M value chains, IoT value chains, An emerging industrial structure for IoT, The international driven global value chain and global information monopolies. M2M to IoT-An Architectural Overview: Building architecture, Main design principles and needed capabilities, An IoT architecture outline, Standard considerations.			9		
Unit 3:	IoT Architecture -State of the Art: Introduction, State of the art, Architecture reference model- Introduction, Reference model and architecture, IoT reference model, IoT Reference Architecture: Introduction, Functional view, Information view, Deployment and operational view, Other relevant architectural views.			9		
Unit 4:	Domain Specific IoT Applications: Home automation, Cities, Environment, Energy, Retail, Logistics, Agriculture, Industry, Health and lifestyle.				8	
Unit 5:	Introduction Contribution platforms for	n, Overview of g n from FP7 project or smart cities, Firs	curity and Governance: overnance, Privacy and s, Security, Privacy and st step towards a secure the IoT in smart cities, Sec	trust in l platform,	IoT-data-	8
		Total	Hours		·	42



Textbook	ts.
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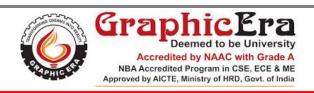
- **1.** Vijay Madisetti and Arshdeep Bahga, "*Internet of Things (A Hands-on-Approach*)", 1st Edition, VPT, 2014.
- 2. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stefan Avesand, Stamatis Karnouskos, David Boyle, "From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence", 1st Edition, Academic Press, 2014.
- Francis daCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Everything", 1st Edition, Apress Publications, 2013.

Reference books

4. Cuno Pfister, "*Getting Started with the Internet of Things*", O'Reilly Media, 2011, ISBN: 978-1-4493-9357-1, 2011.

Mode of Evaluation

Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



	Depa	rtment of Electroni	ics and Communication Er	ngineerin	g		
B. Tech in			on Engineering with Hons Robotics			tems and	
Semester	Seventh	Subject Title	Networking Lab		Code	PEC 759	
Course Components		Credits		L	T	P	
Professional Core Course (PCC)		02	Contact Hours	1	0	2	
Exami	nation	Practical	- Weightage: Evaluation	CWA	MSE	ESE	
Duratio	n (Hrs)	03	Weightage. Evaluation	25	25	50	
		Pre-requisit	e: Sensor Interfacing Lab				
		Co	urse Outcomes				
Upon comp			ents will be able to				
CO 1	Recall the network.	concepts of SENSI	ENUTS and ARDUINO a	nd its ap	plications	in sensor	
CO 2	Understand the interfacing of various sensors with SENSENUT and ARDUINO.						
CO 3	Learn the f	undamentals of IoT	cloud and base station.				
CO 4	Assess and	evaluate interfacing	g of sensors with SENSEN	UT and A	RDUINO	•	
Exp. No.	Name of the Experiment						
1.	To study the working and flow of operation in SENSENUTS.						
2.	To study SENSNUTS GUI and interfacing of SENSNUTS with hardware.						
3.	To study and analyze SENSENUTS with LED.						
<i>4</i> .	To create network setup and measure ambient temperature using SENSENUTS.						
<i>5</i> .	To create network setup and measure ambient humidity using SENSENUTS.						
6.	To monitor and analyze water level using ultrasonic sensor and Arduino Uno.						
<i>7</i> .	To measure and analyze soil humidity using moisture sensor and Arduino Uno.						
8.	To monitor and analyze air pollution using sensor and Arduino Uno.						
9.			g sensor and Arduino Uno.				
10.	To monitor motion in a room using Passive infrared motion sensor and Arduino Uno.						
11.	To create and develop base station using cloud and sense the soil humidity using Arduino platform.						
12.	To impleme	nt the shortest path	algorithm on SENSENUT	platform			
Innovative	Experiment.	<u> </u>					
13.	To create and develop base station using cloud and sense the soil humidity using SENSENUT platform.						
14.		•	suggestion of Lab In charge	e.			

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam	
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