

Department of Electronics and Communication Engineering

Bachelor of Technology

Electronics and Communication
Engineering with Hons. in Embedded
Systems and Robotics

Curriculum

University Vision

We visualize Graphic Era (Deemed to be University) as an internationally recognized, enquiry driven, ethically engaged diverse community, whose members work collaboratively for positive transformation in the world, through leadership in teaching, research and social action.

University Mission

The mission of the university is to promote learning in true spirit and offering knowledge and skills in order to succeed as professionals. The university aims to distinguish itself as a diverse, socially responsible learning community with a high-quality scholarship and academic rigor.

Department Vision

The Department visualizes itself to become leading centre of learning in the field of Electronics & Communication Engineering with academic excellence in research to produce self-motivated, creative, and socially responsible engineers and specialists, ready to take up challenges of industrial development with ethics and societal commitment.

Department Mission

M1: To provide high quality contemporary education in the field of Electronics & Communication Engineering and professional ethics to its learners.

M2: To provide creative learning environment for the students to equip them with strong foundation for continuing higher education.

M3: To pursue research and develop insight knowledge of current and emerging technologies in Electronics & Communication Engineering to serve the needs of the society, industry, and scientific community.

M4: To prepare students to have creative and innovative thinking to develop them into socially responsible professionals

Program Educational Objectives (PEOs):

PEO1	Inculcation of an ability to realize and apply the subject-related knowledge to the real-world problems in the areas of electronics and communication engineering.
PEO2	Motivating individuals for team-led effort to investigate and provide ecologically sustainable, and cost-effective solutions to the problems in the subject area.
PEO3	Encouragement of competence in engineering computational and experimental capabilities to pursue research oriented higher education.
PEO4	Establishment of all-round environment for well conversant, socially and ethically responsible individuals with excellent communication skills.

Program Outcomes (POs):

PO1	Engineering knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
PO2	Problem analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
PO3	Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
PO4	Conduct investigations of complex problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
PO5	Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
PO6	The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
PO7	Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
PO8	Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
PO9	Individual and teamwork: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
PO10	Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
PO11	Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.
PO12	Life-long learning: Recognize the need for and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

Program Specific outcomes (PSOs):

PSO1	Create an ability to understand theoretical and practical concepts of Electronics and Communication Engineering and apply them in designing, fabrication, and testing of various Electronics & Communication system.
PSO2	The ECE Graduates will be able to analyze and implement engineering system pertaining to communication, Signal Processing, VLSI, Radio Frequency communication, microprocessor; microcontroller-based system design and embedded systems etc.
PSO3	This program enables the student to succeed in competitive exam like GATE, IES etc. and provides foundation for higher education and research.



Program Course Structure (All Semesters)

B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2022 onwards)

Semester I & II

	COURSE MODULE				ACHI CRIO		WEIGHTAGE: EVALUATION			
THEORY SUBJECT		CDEDITC	_	T	P	CWA	MSE	ECE	T0T17	
CODE	TITLE	COMPONENT	CREDITS	L	T	r	CWA	MISE	ESE	TOTAL
TEC 101/201	Basic Electronics Engineering	ESC	3	3	0	0	25	25	50	100
LABORA	TORY									
PEC 151/251	Basic Electronics Engineering Lab	ESC	1	0	0	2	25	25	50	100
	TOTAL		4	3	0	2				200



B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2022 onwards)

Semester III

	COURSE M	10DULE			ACHI ERIO		WEIGHTAGE: EVALUATION			
THEOR	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL
CODE	TITLE	COMPONENT	CKEDITS	L	1	Г	CWA	MSE	ESE	IOIAL
TEC 301	Electronic Devices and Circuits	PCC	4	3	1	0	25	25	50	100
TEC 302	Digital Electronics	PCC	3	3	0	0	25	25	50	100
TEC 303	Networks Analysis and Synthesis	PCC	4	3	1	0	25	25	50	100
TEC 304	Signals and Systems	PCC	4	3	1	0	25	25	50	100
TEC 359	Fundamentals of Computer Organization	PCC	3	3	0	0	25	25	50	100
TMA 310	Advanced Engineering Mathematics	BSC	3	3	0	0	25	25	50	100
XCS 301	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 301	Electronics Circuit Lab	PCC	1	0	0	2	25	25	50	100
PEC 302	Digital Electronics Lab	PCC	1	0	0	2	25	25	50	100
GP 301	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		26	20	03	04				1000



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Semester IV

	COURSE M	10DULE		TEACHING PERIODS			WEIGHTAGE: EVALUATION			
THEORY	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL
CODE	TITLE	COMPONENT	CREDITS	L	1		CWA	MISE	ESE	
TEC 401	Communication Systems I	PCC	4	3	1	0	25	25	50	100
TEC 402	Analog Integrated Circuits	PCC	4	3	1	0	25	25	50	100
TEC 403	Microprocessor and its Applications	PCC	3	3	0	0	25	25	50	100
TEC 404	Electromagnetic Field Theory	PCC	4	3	1	0	25	25	50	100
TEC 451	Introduction to Robotics	PCC	3	3	0	0	25	25	50	100
TOE	Open Elective I	OEC	3	3	0	0	25	25	50	100
XCS 401	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABORA	ATORY AND OTHERS									
PEC 401	Communication Systems I Lab	PCC	1	0	0	2	25	25	50	100
PEC 402	Analog Integrated Circuits Lab	PCC	1	0	0	2	25	25	50	100
PEC 403	Microprocessor Lab	PCC	1	0	0	2	25	25	50	100
POE	Open Elective Lab-I	OEC	1	0	0	2	25	25	50	100
GP 401	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		28	20	03	08				1200
Mandato	ry Non - Credit Course									
MC 401	Constitution of India	MC	0	0	0	0	0	0	0	0



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(Batch 2022 onwards) Semester V

	COURSE N	MODULE			TEACHING PERIODS WEIGHTAGE: EVA				: EVALU	LUATION	
THEORY	Y SUBJECTS		CREDITS	L	Т	P	CWA	MSE	ESE	TOTAL	
CODE	TITLE	COMPONENT	CKEDIIS	L	1	1	CWA	141512	ESE	TOTAL	
TEC 501	Digital Signal Processing	PCC	4	3	1	0	25	25	50	100	
TEC 502	Communication Systems II	PCC	4	3	1	0	25	25	50	100	
TEC 503	Microcontroller and Embedded Systems	PCC	3	3	0	0	25	25	50	100	
TEC 504	Antenna and Wave Propagation	PCC	3	3	0	0	25	25	50	100	
TEC 551	Sensor Technology	PCC	3	3	0	0	25	25	50	100	
TEC	Program Elective I	PEC	3	3	0	0	25	25	50	100	
XCS 501	Career Skills	HSMC	2	2	0	0	25	25	50	100	
LABOR	ATORY AND OTHERS										
PEC 501	Digital Signal Processing Lab	PCC	1	0	0	2	25	25	50	100	
PEC 502	Communication Systems II Lab	PCC	1	0	0	2	25	25	50	100	
PEC 503	Microcontroller & Embedded Lab	PCC	1	0	0	2	25	25	50	100	
PEC55 9	Sensors Interfacing Lab	PCC	2	1	0	2	25	25	50	100	
GP 501	General Proficiency	GP	1	0	0	0	-	-	-	100	
	TOTAL		28	21	2	08				1200	



B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2022 onwards) Semester VI

	COURSE M	IODULE			ACHI ERIO		WEIG	GHTAGE	: EVALU	JATION
THEOR	Y SUBJECTS			L	Т	P	CWA	MSE	ESE	тоты
CODE	TITLE	COMPONENT	CREDITS	2	-	-	CWA	MSE	ESE	TOTAL
TEC 601	Wireless Communication	PCC	3	3	0	0	25	25	50	100
TEC 602	Microwave Engineering	PCC	3	3	0	0	25	25	50	100
TEC 603	VLSI Technology and Design	PCC	3	3	0	0	25	25	50	100
TEC 659	Advanced Embedded Systems	PCC	3	3	0	0	25	25	50	100
TEC	Program Elective II	PEC	3	3	0	0	25	25	50	100
TOE	Open Elective II	OEC	3	3	0	0	25	25	50	100
XCS 601	Career Skills	HSMC	2	2	0	0	25	25	50	100
LABOR	ATORY AND OTHERS									
PEC 601	CAD of Electronics using CADENCE Tool Lab	PCC	1	0	0	2	25	25	50	100
PEC 602	Microwave and Antenna Lab	PCC	1	0	0	2	25	25	50	100
POE	Open Elective Lab-II	OEC	1	0	0	2	25	25	50	100
PMP 604	Mini Project	PROJ	1	0	0	2	25	25	50	100
GP 601	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		25	20	0	08				1200



B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2022 onwards)

Semester VII

	COURSE M	IODULE			ACHI ERIO		WEIGHTAGE: EVALUATION			
THEORY	THEORY SUBJECTS			_	Т	P	CWA	MCE	ECE	тоти
CODE	TITLE	COMPONENT	CREDITS	L	1	P	CWA	MSE	ESE	TOTAL
TEC 701	Computer Architecture	PCC	3	3	0	0	25	25	50	100
TEC 759	Internet of Things and Its Applications	PCC	3	3	0	0	25	25	50	100
TEC	Program Elective III	PEC	3	3	0	0	25	25	50	100
TEC	Program Elective IV	PEC	3	3	0	0	25	25	50	100
MC 701	Disaster Management	MC	-	3	0	0	-	-	-	-
LABOR	ATORY AND OTHERS									
PEC 701	Project Phase-I	PROJ	5	0	0	10	100	-	-	100
SEC 701	Seminar on Industrial Training	PROJ	1	0	0	2	100	-	-	100
PEC 759	Networking Lab	PCC	2	1	0	2	25	25	50	100
GP 701	General Proficiency	GP	1	0	0	0	-	-	-	100
	TOTAL		21	16	0	14				800



B. Tech (Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics)

(Batch 2022 onwards) Semester VIII

	COURSE MODULE				TEACHING PERIODS			WEIGHTAGE: EVALUATION				
THEOR	Y SUBJECTS		CREDITS	L	Т	P	CVV	MSE	ESE			
CODE	TITLE	COMPONENT	CKEDIIS	L		1	CWA			TOTAL		
TOE	Open Elective III	OEC	3	3	0	0	25	25	50	100		
TEC	Program Elective V	PEC	3	3	0	0	25	25	50	100		
TEC	Program Elective VI	PEC	3	3	0	0	25	25	50	100		
LABOR	ATORY AND OTHERS											
PEC 801	Project Phase-II	PROJ	9	0	0	18	50		150	200		
GP 801	General Proficiency	GP	1	0	0	0	-	-	-	100		
	TOTAL		19	9	0	18				600		



	Program Elective Courses							
Course Code	Course Name	Semester						
	Program Elective I							
TEC 552	Control Systems							
TEC 553	Electromagnetic Interference and Compatibility	E:AL						
TEC 554	High Speed Communication Circuits	Fifth						
TEC 555	Probability and Stochastic Processes							
	Program Elective II							
TEC 651	Data Communication Networks							
TEC 652	Digital VLSI Circuit Design	Sixth						
TEC 653	Electronic System Design	Sixui						
TEC 654	Digital Video Processing							
	Program Elective III							
TEC 751	Optical Fiber Communications							
TEC 752	ASIC Design and FPGA	Seventh						
TEC 753	Radar and Navigation Aids	Seventin						
TEC 754	Organic Electronics Devices and Circuits							
	Program Elective IV							
TEC 755	Wireless Sensor Network							
TEC 756	Fundamentals of Nanotechnology	Seventh						
TEC 757	CMOS Analog Circuit Design	Seventin						
TEC 758	Speech Processing							
	Program Elective V							
TEC 851	Satellite Communications							
TEC 852	Testing of VLSI circuits	- Eighth						
TEC 853	TEC 853 Digital System using VHDL							
TEC 854	Digital Image Processing							
	Program Elective VI							



TEC 855	Telecommunication Switching	
TEC 856	Neural Networks & Machine Learning	T: -1.41.
TEC 857	Mobile Ad hoc Networks	Eighth
TEC 858	Adaptive Signal Processing	



Open Elective Courses					
Course Code	Semester				
Open Elective-I					
TOE 410	Data Structures with C				
TOE 411	Electrical Machines-I	Fourth			
TOE 412	Computer Based Numerical and Statistical Technique	rourth			
Open Elective Lab-I					
POE 410	Data Structures with C Lab				
POE 411	Electrical Machines Lab-1	Fourth			
POE 412					
Open Elective-II					
TOE 610	Object Oriented Programming with C++				
TOE 611	Power Electronics	Sixth			
TOE 612 Operating Systems					
	Open Elective Lab-II				
POE 610	OOPs with C++ Lab				
POE 611	Power Electronics Lab	Sixth			
POE 612	Operating Systems Lab				
	Open Elective-III				
TOE 810	Principles of Management				
TOE 811	Electrical and Electronics Measuring Instruments	Eighth			
TOE 812	Biosensors and Bioelectronics				



Abbreviations:

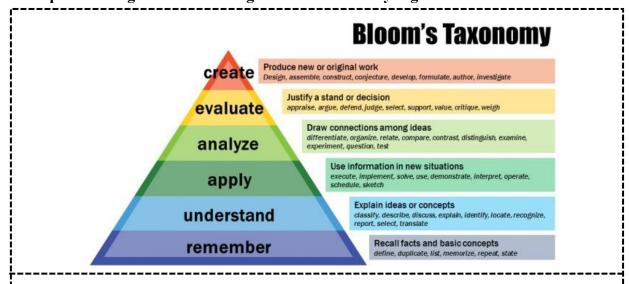
L	Lecture
T	Tutorial
P	Practical
CWA	Class Work Assessment
MSE	Mid Semester Exam
ESE	End Semester Exam
BSC	Basic Science Course
ESC	Engineering Science Course
HSMC	Humanities and Social Sciences including Management course
PCC	Professional Core Course
PEC	Professional Elective Course
OEC	Open Elective Course
MC	Mandatory Course
PROJ	Project
GP	General Proficiency



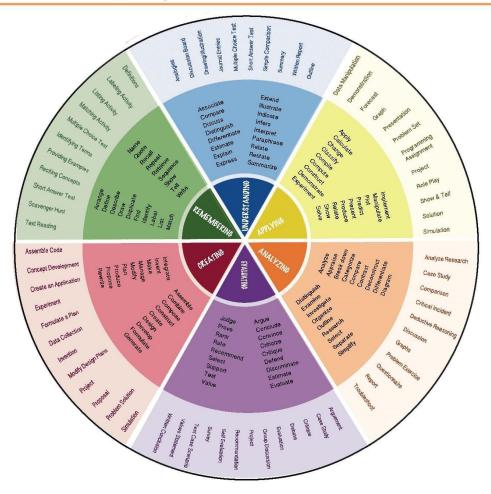
Bloom's Taxonomy for Curriculum Design and Assessment

Preamble

The design of curriculum and assessment is based on Bloom's Taxonomy. A comprehensive guideline for using Bloom's Taxonomy is given below for reference.









Electronics and Communication Engineering Department B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics Fundamentals of Computer TEC Third Subject Title Semester Code Organization 359 Course Components Credits **Contact Hours Professional Core** 03 3 0 0 Course (PCC) Examination Theory MSE **CWA ESE** Weightage: Evaluation Duration (Hrs) 25 25 50 **Pre-requisite:** Basic Electronics Course Outcomes Upon completion of this course, the students will be able to CO 1 Recall the concepts of computer system and its organization. **CO 2 Understand** different Computer Arithmetic operations and algorithms. **Apply** different addressing modes and instruction formats for computer organization. CO 3 Analyse memory organization, cache memory mapping and paging to improve **CO** 4 performance. CO 5 Assess and evaluate processor organization and control unit. **Develop** the concepts of computer organization for better understanding of courses, such CO 6 as embedded system and robotics. Unit No. Content Hours **Introduction:** Structure of a computer system, Functional components of a computer, **Unit 1:** Historical development: First through fourth generation computers, Moore's law, The Von Neumann and Non Von Neumann model. **Machine Instructions:** Memory location and addresses, Operands, Addressing modes, Instruction Unit 2: formats, Instruction sequencing, Execution of a complete instruction, Instruction set architectures - CISC and RISC architectures. **Computer Arithmetic:** Addition and subtraction, Arithmetic circuit, Multiplication algorithms, **Unit 3:** Division algorithms, Floating-point representation, Floating point arithmetic operations, BCD adder. **Processing Unit:** Organization of a processor - Registers, ALU and Control unit, Data path in Unit 4: a CPU, Instruction cycle, Organization of a control unit, Operations of a control unit, Hardwired control unit, Microprogrammed control unit. **Memory Subsystem:** Semiconductor memories, Memory cells - SRAM and DRAM cells, Internal organization of a memory chip, Cache memory unit, Concept of cache Unit 5: 10 memory, Mapping methods, Organization of a cache memory unit, Effective Access time and Hit ratio, Virtual memory, Paging, Advantages and disadvantages of paging. **Total Hours**



	Textbooks				
1.	William Stallings, "Computer Organization & Architecture Designing for Performance",				
	Prentice Hall Education, 8th Edition, 2010.				
2.	Carl Hamacher, ZvonkoVranesic, SafwatZaky, "Computer Organization", Tata McGraw Hill,				
	5 th Edition, 2011				
	Reference Books				
3.	David A. Patterson, John L. Hennessy: "Computer Organization and Design – The Hardware				
	David A. Patterson, John L. Hennessy: " <i>Computer Organization and Design – The Hardware / Software Interface</i> ", Morgan Kaufmann (Elsevier), 5 th Edition, 2013.				
4.	John P. Hayes, "Computer Architecture and Organization", Tata McGraw Hill, 3rd Edition,				
	2012.				

Mode of Evaluation	Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



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www.geu.ac.in Electronics and Communication Engineering Department B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics TEC Semester Fourth Subject Title Introduction to Robotics Code 451 Course Components Credits T P L **Professional Core Contact Hours** 03 3 0 0 Course (PCC) Theory **CWA** MSE **ESE** Examination Weightage: Evaluation **Duration** (Hrs) 25 50 Pre-requisite: Basic Electronics Engineering Course Outcomes Upon completion of this course, the students will be able to CO 1 Retrieve the history, concepts, and key components of robotics technology. CO 2 **Understand** the control systems related to robotics. CO 3 Model and control single joint robot. **CO** 4 **Understand** various robot sensors, end effectors and their perception principles. CO 5 **Analyse** the robot kinematics, navigation, and path planning. CO 6 Understand machine vision and its digitizing function. Unit No. Content Hours **Fundamentals of Robotics: Unit 1:** Brief history of robotics, Robotics market, Future perspectives of robotics, robot anatomy, Robot drive systems, Precision of movement, End effectors. **Control System and Components:** Basic control system concepts and model, Controllers, Robot sensors and Unit 2: actuators, Velocity sensors, Power transmission system, Modelling and control of single joint robot. **Robot End Effectors and Sensors:** Unit 3: Types of end effectors, Mechanical grippers, other types of grippers, 12 Robot/end effectors interface, Transducers, and sensors. **Robot Motion Analysis and Control:** Introduction to manipulator kinematics, Homogeneous transformation, Unit 4: Robot kinematics, Manipulator path control, Robot dynamics. Machine Vision: Introduction to machine vision, Sensing and digitizing function in machine **Unit 5:**

	Textbooks					
1.	M P Groover, "Industrial Robotics", TMH, 2 nd Edition, 2012.					
2.	S R Deb and Sankha Deb, " <i>Robotics Technology and Flexible Automation</i> ", TMH, 2 nd Edition, 2010.					
	Reference books					
3.	S.K Saha, "Introduction to Robotics", TMH, 2 nd Edition, 2014					
4.	R.K. Mittal, I. J. Nagrath, "Robotics & Control", TMH, 2005.					

Total Hours

vision, Image processing and analysis.

40



5. Craig. J. J, "*Introduction to Robotics- Mechanics and Control*", Pearson Education India, 3rd Edition, 1999.

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



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K Tech ii			on Engineering with Hons			tems and
B. Teen ii	i Diccironic	, una Communication	Robotics	, in Lino	cuucu Sys	iems unu
Semester	Fifth	Subject Title	Sensor Technolog	у	Code	TEC 551
Course Co	omponents	Credits		\boldsymbol{L}	T	P
Professio Course		03	Contact Hours	3	0	0
Exami	ination	Theory	Weightage: Evaluation	CWA	MSE	ESE
Duratio	n (Hrs)	03	weightage. Evaluation	25	25	50
	Pre-requisite: Basic Physics and Basic Electronics Engineering					
			urse Outcomes			
Upon com	pletion of th	nis course, the stude	ents will be able to			
CO 1	Develop th	e knowledge about t	he basic characteristics of	sensors.		
CO 2		d the working princi				
CO 3			th various electronic device			
CO 4	Apply the sensors.	concepts of sensor t	echnology in several types	s of motio	on and disp	placement
CO 5	Evaluate s	ensors and interfacir	ng circuits			
CO 6	Utilize sens	sors in different engi	neering applications.			
Unit No.	. Content					
Unit 1: Sensor Characteristics: Transfer function, Calibration, Span (Full-scale input), Full-scale output, Calibration error, Accuracy, Hysteresis error, Nonlinearity, Saturation, Repeatability, Dead band, Resolution, Reliability, Uncertainty.						8
	Physical Principles of Sensing: Electric charges, Fields and potentials, Capacitance, Magnetism: Faraday law, Solenoid, Toroid, Induction Resistance, Piezoelectric effect, Pyroelectric effect, Hall effect, Thermoelectric effect, Sound waves, Temperature, Dynamic models of sensor elements, Optical components of sensor.					O
Unit 2:	Electric ch law, Sole Pyroelectric Temperatur	rinciples of Sensing arges, Fields and po- noid, Toroid, Ind c effect, Hall effe	lution, Reliability, Uncertage: extentials, Capacitance, Maluction Resistance, Pieset, Thermoelectric effect	ngnetism: zoelectric t, Sound	Faraday effect, waves,	8
Unit 2: Unit 3:	Electric ch law, Sole Pyroelectric Temperatur sensor. Interface I Input char converters, Inherent no	rinciples of Sensing arges, Fields and ponoid, Toroid, Inc. c effect, Hall effect, Dynamic models Electronic Circuits: acteristics of interfaction circuits, April 2015, Transmitted in the control of th	continuous Reliability, Uncerta diution, Reliability, Uncerta continuous Resistance, Ma diution Resistance, Pie ect, Thermoelectric effect of sensor elements, Option	agnetism: zoelectric t, Sound cal compo Light to s, Noise ir Bypass ca	Faraday effect, waves, onents of voltage sensors:	
	Electric ch law, Sole Pyroelectric Temperatur sensor. Interface I Input char converters, Inherent no Magnetic s Motion an Ultrasonic sensors, Ca	rinciples of Sensing arges, Fields and ponoid, Toroid, Incomplete of Electronic Circuits: acteristics of interference Excitation circuits, Poise, Transmitted no hielding, Mechanica d Displacement Sendetectors, Optoeles pacitive sensors, Incomplete of Electronic Circuits, Poise, Transmitted no hielding, Mechanica d Displacement Sendetectors, Optoeles pacitive sensors, Incomplete of Electronic Circuits (Circuits).	contentials, Capacitance, Maduction Resistance, Pieset, Thermoelectric effect of sensor elements, Option acce circuits, Amplifiers, Analog to digital converters oise, Electric shielding, Il noise, Ground planes, Se	agnetism: zoelectric t, Sound cal compo Light to s, Noise ir Bypass ca ebeck noi s, Poten or: LVDT	Faraday effect, waves, onents of voltage a sensors: apacitors, se	8
Unit 3:	Electric ch law, Sole Pyroelectric Temperatur sensor. Interface I Input char converters, Inherent no Magnetic s Motion an Ultrasonic sensors, Ca Eddy curre Humidity	rinciples of Sensing arges, Fields and ponoid, Toroid, Incomplete of Electronic Circuits: acteristics of interferent Excitation circuits, Poise, Transmitted not hielding, Mechanica detectors, Optoeles apacitive sensors, Incomplete of Electronic Circuits, Poise, Transmitted not hielding, Mechanica detectors, Optoeles apacitive sensors, Incomplete of Electronic Circuits, Poise, Transmitted not be apacitive sensors, Incomplete of Electronic Circuits, Poise, Transversensors, Transversensors and Light Incomplete of Electrical Circuits, Flectrical Circuit	contentials, Capacitance, Maluction Resistance, Pier ett, Thermoelectric effect of sensor elements, Option acce circuits, Amplifiers, Analog to digital converters oise, Electric shielding, Fal noise, Ground planes, Sensor: Extremic motion detector ductive and magnetic sensors is einductive sensor, Hall et al.	agnetism: zoelectric t, Sound cal compo Light to s, Noise ir Bypass ca ebeck noi s, Poten or: LVDT ffect sense	Faraday effect, waves, onents of voltage a sensors: apacitors, se tiometric r, RVDT, or.	8

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Text	4 I.	_	~	I
IUV	rn	•	"	u v



1. Jacob Fraden, "*Handbook of modern sensors: physics, designs, and applications*", Springer, 4th Edition, 2005

Reference books

- 2. C.M. Kyung, H. Yasuura, Y. Liu, Y. L. Lin, "Smart Sensors and Systems: Innovations for Medical, Environmental, and IoT Applications", Springer, 2016.
- 3. Jon Wilson, "Sensor Technology Handbook", Volume 1, Elsevier, 2004.

Mode of Evaluation Test / Quiz / Assignment / Mid Term Exam / End Term Exam.



Department of Electronics and Communication Engineering							
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and							
Robotics							
Semester	Fifth	Subject Title	Sensors Interfacing I	Lab	Code	PEC 559	
Course Co	mponents	Credits		\boldsymbol{L}	T	P	
Professio Course		02	Contact Hours	1	0	2	
Exami	nation	Practical	Wain later on Freedom dine	CWA	MSE	ESE	
Duratio	n (Hrs)	03	Weightage: Evaluation	25	25	50	
		Pre-requisite: Mic	roprocessor and its applica	tions			
		Со	urse Outcomes				
Upon com	oletion of th	nis course, the stude	ents will be able to				
CO 1	Recall the sensors.	basic concepts of T	TM4C123GXL, MSP430G	2, Ardui	no Uno ar	nd various	
CO 2	Understand the concepts of interfacing of sensors with Texas boards and Arduino Boards.						
CO 3	Analysevarious interfacing boards with IoT.						
CO 4	Apply various transducers and actuators interfacing in the designing of embedded and IoT systems.						
Exp. No.	Name of the Experiment						
1.	Familiariza	tion of TIVA C-seri	es12 launch pad (TM4C12	3GXL)			
2.	Interfacing of sensors with TIVA C-series12 launch pad (TM4C123GXL)						
3.	Interfacing of sensors with cloud using TIVA C-series12 launch pad (TM4C123GXL)						
4.	Interfacing of keypad with TIVA C-series12 launch pad (TM4C123GXL)						
5.	Familiarization of MSP430G2 launch pad.						
<i>6</i> .	Interfacing of sensors with MSP430G2 launch pad.						
<i>7</i> .	Interfacing	of sensors with clou	d using MSP430G2 launch	n pad.			
8.	Interfacing	of keypad with MSI	P430G2 launch pad.				
9.	Familiariza	tion of Arduino Mic	rocontroller.				
<i>10</i> .	Interfacing	of sensors with Ard	uino Microcontroller.				
<i>11</i> .	Interfacing	of keypad with Ard	uino Microcontroller.				
12.	Interfacing	of servo motor with	TIVA C-series 12 launch p	oad (TM4	C123GXL	L)	
Innovative	Experimen	t:					
13.	Interfacing	of servo motor with	MSP430G2				
14.	Any other	experiment with the	suggestion of Lab In charg	ge.			

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Electronics and Communication Engineering Department							
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics							
Semester	Sixth	Subject Title	Advanced Embedded S	ystems	Code	TEC 659	
Course Co	omponents	Credits		L	T	P	
Professio Course	onal Core (PCC)	03	Contact Hours	3	0	0	
Exami	nation	Theory	Weightage: Evaluation	CWA	MSE	ESE	
Duratio	n (Hrs)	03	Weightage. Livatuation	25	25	50	
			ocontroller & Embedded Sy	ystems			
			urse Outcomes				
	•	nis course, the stude					
CO 1			microprocessor and microc				
CO 2			d instruction sets of PIC m		rollers.		
CO 3			n design and peripheral into	erfacing.			
CO 4	Analyse sta	ructure of RTOS in I	Embedded Systems.				
CO 5	Evaluate PIC and ARM processors as the advanced series.						
CO 6 Integrate the concepts of embedded systems for developing projects.							
Unit No.	. Content					Hours	
Unit 1:	Introduction to Embedded systems: Embedded systems vs. General computing systems, History of embedded systems, Classification, Application area. Typical embedded systems, Characteristics and quality attributes of embedded systems.					8	
Unit 2:	Intel Family of Microcontrollers PIC Architectures:					8	
Unit 3: System Design, Peripheral Interfacing: Unit 3: Digital and analog interfacing, Programming framework, Software development.					Software	8	
Unit 4: Real Time Operating Systems (RTOS): Embedded systems design, Operating system basics, Types of operating system tasks, Process, Threads, Multiprocessing and Multitasking, Task scheduling.						8	
Unit 5:	ARM 32-		rs: bus architecture, Brief itecture and overview.	introdu	ection to	8	
		Total	Hours			40	

	Textbooks					
1.	Raj Kamal, "Microcontrollers: Architecture, Programming, Interfacing and System Design",					
	Pearson Education India, 2 nd Edition, 2005.					
2.	J. Morton, "The PIC Microcontroller", Newnes, 3rd Edition, 2005.					
	Reference Books					
3.	A. Sloss, D. Symes, C. Wright, "Arm System Developer's Guide: Designing and optimizing					
	system software", Morgan Kauffman Publisher, Illustrated edition, 2004.					



4. K. V. Shibhu, "Introduction to Embedded Systems", Tata McGraw Hill, 1st Edition, 2009.

5. Frank Vahid, Tony Givargis, "*Embedded System Design, A Unified Hardware, Software Approach*", Wiley Publications, 3rd Edition, 1999.

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	Fla	otvonies and Commi	unication Engineering De	navtman	,		
Electronics and Communication Engineering Department B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and							
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics							
Semester	Seventh	Subject Title	Internet of Things and Applications	d Its	Code	TEC 759	
Course Co	omponents	Credits		\boldsymbol{L}	T	P	
Professional Core Course (PCC) 03 Contact Hours 3 0				0	0		
Exam	Examination Theory Weightage Englishing CWA MSE			MSE	ESE		
Duratio	on (Hrs)	03	Weightage: Evaluation	25	25	50	
Pre-requisite: Wireless Communication							
		Coi	urse Outcomes				
		is course, the stude					
CO 1			ss sensor network and Inter	rnet of the	ings.		
CO 2		l IoT Market perspe					
CO 3		State of the Art – IoT					
CO 4		applications of IoT.					
CO 5			ations for privacy, security	, and gov	ernance.		
CO 6	Design and	develop various IoT	based applications.				
	~						
Unit No.	Content					Hours	
Unit 1:	Introduction to IoT: Introduction to sensor networks, Unique constraints and challenges, Advantage of sensor networks, Defining IoT, Characteristics of IoT, Physical design of IoT: Things in IoT, Physical design, Logical design of IoT, Functional blocks of IoT, IoT communication models, Applications of sensor networks in IoT.						
 M2M to IoT – A Basic Perspective: Introduction, some definitions, M2M value chains, IoT value chains, An emerging industrial structure for IoT, The international driven global value chain and global information monopolies. M2M to IoT-An Architectural Overview: Building architecture, Main design principles and needed capabilities, An IoT architecture outline, Standard considerations. 					9		
Unit 3:	IoT Architecture -State of the Art: Introduction, State of the art, Architecture reference model- Introduction, Reference model and architecture, IoT reference model, IoT Reference Architecture: Introduction, Functional view, Information view, Deployment and operational view, Other relevant architectural views.					9	
Unit 4:	Home auto Agriculture	, Industry, Health an	Environment, Energy, I d lifestyle.	Retail, I	Logistics,	8	
Unit 5:	Introduction Contribution platforms for	n, Overview of g n from FP7 project or smart cities, Firs	curity and Governance: overnance, Privacy and s, Security, Privacy and st step towards a secure the IoT in smart cities, Sec	trust in l platform,	loT-data-	8	
		Total	Hours			42	



Textbooks

- 1. Vijay Madisetti and Arshdeep Bahga, "Internet of Things (A Hands-on-Approach)", 1st Edition, VPT, 2014.
- 2. Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stefan Avesand, Stamatis Karnouskos, David Boyle, "From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence", 1st Edition, Academic Press, 2014.
- 3. Francis daCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Everything", 1st Edition, Apress Publications, 2013.

Reference books

4. Cuno Pfister, "*Getting Started with the Internet of Things*", 1st Edition, O'Reilly Media, 2011, ISBN: 978-1-4493-9357-1, 2011.

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Department of Electronics and Communication Engineering							
B. Tech in Electronics and Communication Engineering with Hons. in Embedded Systems and Robotics							
Semester	Seventh	Subject Title	Networking Lab		Code	PEC 759	
Course Components		Credits	Contact Hours	L	T	P	
Professional Core Course (PCC)		02		1	0	2	
Examination		Practical	Weightage: Evaluation	CWA	MSE	ESE	
Duration (Hrs)		03		25	25	50	
<i>Pre-requisite:</i> Sensor Interfacing Lab							
Course Outcomes							
Upon completion of this course, the students will be able to							
CO 1	Recall the concepts of SENSENUTS and ARDUINO and its applications in sensor network.						
CO 2	Understand the interfacing of various sensors with SENSENUT and ARDUINO.						
CO 3	Learn the fundamentals of IoT cloud and base station.						
CO 4	Assess and evaluate interfacing of sensors with SENSENUT and ARDUINO.						
Exp. No.	Name of the Experiment						
1.	To study the working and flow of operation in SENSENUTS.						
2.	To study SENSNUTS GUI and interfacing of SENSNUTS with hardware.						
3.	To study and analyze SENSENUTS with LED.						
4.	To create network setup and measure ambient temperature using SENSENUTS.						
5.	To create network setup and measure ambient humidity using SENSENUTS.						
6.	To monitor and analyze water level using ultrasonic sensor and Arduino Uno.						
<i>7</i> .	To measure and analyze soil humidity using moisture sensor and Arduino Uno.						
8.	To monitor and analyze air pollution using sensor and Arduino Uno.						
9.	To monitor light intensity using sensor and Arduino Uno.						
<i>10</i> .	To monitor motion in a room using Passive infrared motion sensor and Arduino Uno.						
11.	To create and develop base station using cloud and sense the soil humidity using Arduino platform.						
12.	To impleme	ent the shortest path	algorithm on SENSENUT	platform.			
Innovative	Experiment						
13.	To create and develop base station using cloud and sense the soil humidity using SENSENUT platform.						
<i>14</i> .	Any other experiment with the suggestion of Lab In charge.						

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